

Multivariable Calculus Formulæ

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Part I

Line Integrals

1 Scalar

When f is the function being integrated, s is arc length, C is the curve to integrate along which is continuous from a to b and \mathbf{r} is the parametrization of C :

$$\int_C f \, ds = \int_a^b f(x(t), y(t), z(t)) |\mathbf{r}'(t)| \, dt$$

2 Vector Fields

There are a number of notations for line integrals of vector fields shown below where $\mathbf{F} = \langle f, g, h \rangle$ is the vector field and \mathbf{T} is the unit tangent vector to the curve C which is continuous from a to b and parametrized by \mathbf{r} :

$$\begin{aligned} \int_C \mathbf{F} \cdot \mathbf{T} \, ds &= \int_a^b \mathbf{F} \cdot \mathbf{r}'(t) \, dt \\ &= \int_C \mathbf{F} \cdot d\mathbf{r} \\ &= \int_a^b (f x'(t) + g y'(t) + h z'(t)) \, dt \\ &= \int_C f \, dx + g \, dy + h \, dz \end{aligned}$$

3 Applications

3.1 Circulation

Circulation is simply expressed as a line integral of a vector field. The circulation of \mathbf{F} on curve C is simply $\int_C \mathbf{F} \cdot \mathbf{T} ds$.

3.2 Flux

Flux is expressed as follows, where \mathbf{n} is the unit normal vector:

$$\begin{aligned}\int_C \mathbf{F} \cdot \mathbf{n} ds &= \int_a^b (f y'(t) - g x'(t)) dt \\ &= \int_C f dy - g dx\end{aligned}$$

4 Green's Theorem

4.1 Circulation Form

Let C be a simple closed smooth curve, oriented counterclockwise, that encloses a connected and simply connected region R in the plane. Assume $\mathbf{f} = \langle f, g \rangle$, where f and g have continuous first partial derivatives in R .

$$\oint_C \mathbf{F} \cdot d\mathbf{r} = \iint_R \left(\frac{\partial g}{\partial x} - \frac{\partial f}{\partial y} \right) dA$$

4.1.1 Two-Dimensional Curl

In the double integral from the circulation form formula, the factor of the integral, $\frac{\partial g}{\partial x} - \frac{\partial f}{\partial y}$, is called the two-dimensional curl. This represents the amount of circulation per unit area. Curl can be generalized to $\nabla \times \mathbf{F}$ where $\nabla = \langle \frac{\partial}{\partial x}, \frac{\partial}{\partial y}, \frac{\partial}{\partial z} \rangle$.

4.1.2 Calculating Area

Area can be calculated using Green's Theorem. The area of the region R enclosed by curve C can be calculated as such:

$$\begin{aligned} A &= \iint_R dA \\ &= \oint_C x \, dy \\ &= - \oint_C y \, dx \\ &= \frac{1}{2} \oint_C (x \, dy - y \, dx) \end{aligned}$$

4.2 Flux Form

Under the same conditions as the circulation form where \mathbf{n} is the unit normal vector:

$$\oint_C \mathbf{F} \cdot \mathbf{n} \, ds = \iint_R \left(\frac{\partial f}{\partial x} + \frac{\partial g}{\partial y} \right) dA$$

4.2.1 Two-dimensional Divergence

In the double integral from the flux form formula, the factor of the integral, $\frac{\partial f}{\partial x} + \frac{\partial g}{\partial y}$, is called the two-dimensional divergence. This measures flux per unit area. Divergence can be generalized to $\nabla \cdot \mathbf{F}$ where $\nabla = \langle \frac{\partial}{\partial x}, \frac{\partial}{\partial y}, \frac{\partial}{\partial z} \rangle$.

Part II

Surface Integrals

5 Scalar

Where f is a continuous function on smooth surface S parametrized by $\mathbf{r}(u, v) = \langle x(u, v), y(u, v), z(u, v) \rangle$, $R = \{(u, v) \mid a \leq u \leq b, c \leq v \leq d\}$, $\mathbf{t}_u = \frac{\partial \mathbf{r}}{\partial u}$ and $\mathbf{t}_v = \frac{\partial \mathbf{r}}{\partial v}$,

$\mathbf{n} = \mathbf{t}_u \times \mathbf{t}_v$, then:

$$\iint_S f(x, y, z) dS = \iint_R f(x(u, v), y(u, v), z(u, v)) |\mathbf{t}_u \times \mathbf{t}_v| dA$$

If $f(x, y, z) = 1$ then the resulting integral is the surface area of S .

The following shortcut can also be used when the function is explicitly defined as $z = g(x, y)$:

$$\iint_S f(x, y, z) dS = \iint_R f(x, y, g(x, y)) \sqrt{z_x^2 + z_y^2 + 1} dA$$

6 Vector Fields

Suppose $\mathbf{F} = \langle f, g, h \rangle$ is a continuous vector field on a region of \mathbf{R}^3 containing a smooth oriented surface S . If S is defined parametrically as $\mathbf{r}(u, v)$, then:

$$\iint_S \mathbf{F} \cdot \mathbf{n} dS = \iint_R \mathbf{F} \cdot (\mathbf{t}_u \times \mathbf{t}_v) dA$$

If S is defined as $z = g(x, y)$, then the following shortcut can be used:

$$\iint_S \mathbf{F} \cdot \mathbf{n} dS = \iint_R (-f z_x - g z_y + h) dA$$

6.1 Stokes' Theorem

Let S be a smooth oriented surface in \mathbf{R}^3 with a smooth closed boundary C whose orientation is consistent with that of S . Assume that $\mathbf{F} = \langle f, g, h \rangle$ is a vector field whose components have continuous first partial derivatives on S .

$$\oint_C \mathbf{F} \cdot d\mathbf{r} = \iint_S (\nabla \times \mathbf{F}) \cdot \mathbf{n} dS$$

where \mathbf{n} is the unit vector normal to S determined by the orientation of S .

6.2 Divergence Theorem

Let \mathbf{F} be a vector field whose components have continuous partial derivatives in a connected and simply connected region D enclosed by a smooth oriented surface S . Then:

$$\oiint_S \mathbf{F} \cdot \mathbf{n} \, dS = \iiint_D \nabla \cdot \mathbf{F} \, dV$$

where \mathbf{n} is the unit outward normal vector on S .